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MODELING INTERRILL EROSION ON UNPAVED ROADS IN THE LOESS PLATEAU OF CHINA

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ABSTRACT

Unpaved roads play an important role in soil loss in small watersheds. In order to assess the impact of these unpaved roads in the Loess Plateau of China, runoff and sediment yields from road-related sources must be quantified. Field rainfall simulation experiments were conducted under three slope gradients and five rainfall intensities on unpaved loess roads in a small watershed. Results showed that the runoff generation was very fast in loess road surface (time to runoff < 1 min) and produced a high runoff coefficient (mean value > 0.8). Soil loss rates were decreased as surface loose materials were washed away during a rainstorm. Rainfall intensity, initial soil moisture, and slope gradient are key factors to model surface runoff and sediment yield. Soil loss on loess road surface could be estimated by a linear function of stream power ($R^2 = 0.907$). Four commonly interrill erosion models were evaluated and compared, and the interrill erodibility adopted in the Water Erosion Prediction Project model was determined as 1.34×10^6 (kg s m⁻⁴). A new equation taking into account different parameters like rainfall intensity, surface flow discharge, and slope gradient was established. Copyright © 2013 John Wiley & Sons, Ltd.

KEYWORDS: unpaved road; interrill erosion; runoff; rainfall simulation; the Loess Plateau; China

INTRODUCTION

During the last century, rural roads have been greatly expanded (Leh et al., 2013). It is well known that unpaved rural roads contribute significantly to soil loss in agricultural watersheds despite representing a small fraction of watershed-occupied areas (Dunne, 1979). Comparing with other agricultural land, sealed road surfaces may increase the generation of Hortonian overland flow by decreasing soil infiltration capacity and increasing the production of loose materials as caused by heavy traffic (Dunne, 1979; Ziegler et al., 2000b; Croke & Mockler, 2001). Recently, exacerbated soil losses after roads constructions have been reported in many parts of the world, including USA, England, Kuwait, Norway, South Africa, Tunisia, and China (Leh et al., 2013; Posthumus et al., 2011; Al-Awadhi, 2011; Tømmervik et al., 2012; Foster et al., 2012; Desprats et al., 2013; Xu et al., 2009). Particularly in the Loess Plateau of China, where general sediment yields have been partly controlled by conservation practices (Zhao et al., 2013), unpaved road networks play an increasingly important role in sediment generation at catchment scale (Cao et al., 2009; Liu et al., 2010). A quantitative description of runoff and sediment yields from roadrelated sources is therefore critical (Xu et al., 2009).

Road-related erosion can be monitored at different scales and evaluated by different approaches (Desprats *et al.*, 2013). Field monitoring under natural rainfall conditions is the conventional method to study runoff characteristics and sediment yield from road sediment sources (Reid & Dunne, 1984; Luce & Black, 1999; MacDonald et al., 2001; Xu et al., 2009). However, accurate measurements of the soil loss process during natural rainstorms are nearly impossible. Rainfall simulation is thus an efficient complementary method, which has the advantage of being less time consuming, more controlled, and lower in cost (Meyer, 1994). In spite of the limitations such as small plot scale, simulated rainfall has been adopted to explore road-related runoff and soil loss processes throughout the world (Elliot et al., 1995; Croke et al., 1999; Ziegler et al., 2000b; Arnáez et al., 2004). These studies have described the characteristics of road-related runoff and the sediment generation process (Croke et al., 1999; Ziegler et al., 2000b; Arnáez et al., 2004; Cerdà, 2007), compared soil loss rates for different portions of unpaved roads (Jordán & Martínez-Zavala, 2008; Jordán et al., 2009), and analyzed the seasonal variability of road-related runoff and soil loss (Martínez-Zavala et al., 2008). Many studies have also shown that soil erosion models can provide reasonable estimations of runoff and erosion from road surfaces (Elliot et al., 1995). A growing body of research has focused on rainfall simulation model application and validation for unpaved roads (Elliot et al., 1995; Ziegler et al., 2001), and factors such as road surface interrill erodibility have been explored (Ziegler et al., 2000a; Sheridan et al., 2008; Foltz et al., 2009).

These studies have made progress on the quantification of the road surface soil loss process. However, most of the

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experiments were conducted on relatively low slope gradients (less than 26.8%), whereas the landform in the Loess Plateau is characterized by its steep slope gradient (Cao et al., 2011). Soil loss predicting equations can lead to large errors when extrapolated beyond the range of slope gradients, which used to generate the equations (Liu et al., 1994). Thus, the existing relationships cannot be used without modification in the evaluation of road erosion for the Loess Plateau. Liu et al. (2010) constructed 26.8% slope loess road sections in the laboratory and studied the efficacy of grass on mitigating runoff and erosion under simulated rainfall. However, the laboratory conditions are different from real unpaved roads in vehicle disturbance and compaction. Furthermore, their experiments were conducted using just one slope gradient; therefore, they are unable to represent the worth of different slope gradients on runoff generation and road surface soil loss. Cao et al. (2011) have conducted field runoff simulation experiments on unpaved loess road surfaces and calculated rill erodibility, enabling a prediction of soil loss. However, the prediction of interrill erosion of loess road surfaces has not been well addressed. Hence, experiments carried out on unpaved road surfaces with different slope gradients are still needed. Parametric models need to be developed in order to use erosion models such as Water Erosion Prediction Project (WEPP) on road surfaces.

The objectives of this study were to: (i) study the characteristics of runoff and sediment generation processes; and (ii) develop equations and quantify parameters that can be helpful in predicting interrill soil loss on loess road surfaces. The results provide a background for developing a physically based model for erosion of unpaved roads on the Loess Plateau of China.

MATERIAL AND METHODS

Study Area

All experiments were performed on surfaces of unpaved loess roads in the Danangou watershed near the Ansai Research Station of Soil and Water Conservation, Chinese Academy of Sciences, which is located in the center of the Loess Plateau of China (36°53'N, 109°19'E). The average temperature is 8.8 °C, and monthly averages range from 22.5 °C in July to -7 °C in January. The annual precipitation is 562 mm, and 60% of the rainfall occurs between July and September. The watershed has an altitude between 1,000 and 1,350 m asl; the topography is sharply ridged, and hills rise and fall abruptly. The soil has been developed from loess (Zhao et al., 2013), which is prone to erosion; its erosion rate is high and estimated as $100-120 \text{ Mg ha}^{-1} \text{ yr}^{-1}$ from the catchment measurement (Song et al., 1989). The study area is an agricultural watershed in which large numbers of unpaved roads are constructed for farming, quarrying, and other activities. Determined by the underlying topography, steep road sections can be found throughout the watershed. During a rainstorm, runoff and sediment are commonly rerouted and enhanced by road networks (Xu et al., 2007).

Experiments were conducted on a 3-m-wide unpaved orchard road from August to September 2009. The road was constructed for harvesting purposes 10 years before the experiments were carried out by moving surface soil downhill using a crawler tractor; in the process, road surface was compacted. The road only received occasional disturbance by small vehicles during the harvest. Thus, it could be classified as a secondary road according to Cao *et al.* (2009). Three segments with slope gradients of 10.5%, 17.6%, and 26.8% were selected to represent roads on gentle, mild, and steep slopes in the study area, respectively. There was no evidence of wheel tracks or rills on road surfaces. Soil texture near the experiment site was 10.25% sand (2–0.05 mm), 72.10% silt (0.05–0.002 mm) and 17.65% clay (Fu *et al.*, 2003).

Rainfall Simulation Experiments

Experiments were carried out using a rainfall simulator that was modified on the basis of Meyer & Harmon (1979). As shown in Figure 1, the 2.5-m-long trough rainfall simulator was set with steel frame in the direction of the road. Three Spraying Systems Veejet 80100 nozzles (Spraying Systems Co. Wheaton, Illinois, USA) were assembled with 1.1 m interval on the trough with a water pressure of 40 kPa. Nozzles could swing and generate continuous rainfall intensity. The swing frequency could be changed by an impulse signal through a controller. In this way, rainfall intensity could be changed automatically. Water not sprayed to the plot was recirculated within the trough. When the nozzles reached a height of 2.5 m, simulated rainfall intensity showed a high spatial uniformity (Xie et al., 2008). According to our calibration results, the uniformity coefficient (1 standard deviation/ mean) of rainfall intensity was calculated as 0.9 within the $1 \cdot 1 \text{ m}^2$ rectangular area (50 × 220 cm) that was directly under the rainfall simulator. The rectangular area was marked on the road surface, and the plot boundaries were defined by connecting 30-cm-length and 15-cm-height iron sheets together. Because the compacted road surface was firm and



Figure 1. Sketch and construction of the experimental field plot. This figure is available in colour online at wileyonlinelibrary.com/journal/ldr.

was also easily disturbed, iron sheets were folded into an "L" shape and fixed to the road surface by mud. A 15-cmheight wooden plank was then placed at the higher end to prevent water from flowing into the plot. A gutter was placed at the lower end of the plot to collect runoff and sediment samples. Finally, clear water was supplied through a 2·5-cm-diameter fire nylon hose by a 370 W pump. The pump and the rainfall simulator were driven by a 3·6 kW 220 V gasoline generator. Rainfall intensity in this study was set at 43·8, 68·4, 83·4, 128·4, and 142·2 mm h⁻¹.

Experimental Design

Before each experiment, three soil samples were taken using an iron cylinder (5 cm height and 5 cm diameter) along the plot edge. Soil samples were then oven-dried at 105 °C for 24 h to measure soil moisture and bulk density. The slope angle of each plot was determined using a clinometer. For each experiment, a rainfall simulation thunderstorm was performed for 30 min, and surface runoff was collected and measured by sampling bottles at 1-min intervals. The sampling duration was recorded to determine the flow rate. Sampled sediment was oven-dried at 105 °C for 24 h to determine the runoff sediment concentration. By integrating the runoff and sediment concentration over time, total runoff and soil loss were determined. Each plot was used once, and new plots were set on different undisturbed surfaces to achieve the same initial conditions. Finally, 15 valid experiments comprising the combination of five rainfall intensities and three slope gradients were conducted.

Consolidated and compacted road surfaces have been reported hard to be detached and need relatively high critical shear stress to initiate rills (Cao et al., 2009). Because of the small scale and the short length of the field plots, no rill erosion was expected on the experimental road surfaces. The processes during rainfall simulation could thus be treated as interrill erosion, which was mainly caused by raindrop splash and overland flow transportation. The small size of the plots allows measurements of soil erodibility, infiltration, and runoff, which are representative of the interrill scale soil erosion processes (Cerdà, 1998; Cerdà et al., 2009). Considering the difficulty of accurately measuring surface hydraulic parameters such as runoff speed in interrill areas, the stream power concept was applied, obviating the need for runoff speed data (Nearing et al., 1997). It was calculated as follows (Hairsine & Rose, 1992):

$$\omega = \rho g S q \tag{1}$$

where ω is stream power (g s⁻³), ρ is density of water (g cm⁻³), g is gravitational constant (cm s⁻²), S is slope gradient (m m⁻¹), and q is unit discharge of runoff (cm² s⁻¹). Stream power is the factor that affects the effect of both slope steepness and runoff rate on soil loss (Huang, 1995).

Four generally used interrill erosion models were applied in order to explore interrill erodibility and predict soil loss on the loess road surface. The equation and source of each model is described in Table I. Among them, model 1 was adopted in the WEPP model to predict interrill erosion.

Data Analysis

The effects of slope steepness, soil water content, and bulk density on road surface runoff and soil loss were analyzed. The Pearson correlation coefficient was used to evaluate the relationship between hydrological and soil loss parameters and the influencing factors. Results were reported at the $\alpha = 0.05$ level of significance. The coefficient of determination (R²) and model efficiency (ME) was used to evaluate the performance of the applied models. ME was calculated using the following equation (Nash & Sutcliffe, 1970):

$$ME = 1 - \frac{\sum (Q_i - Q_c)^2}{\sum (Q_i - Q_m)^2}$$
(2)

where ME is model efficiency, an ME value of 1 indicates perfect agreement between measured and calculated values and an ME value of <1 indicates a less strong correlation, Q_i is the measured value, Q_c is the calculated value, and Q_m is the mean value of the measured values. All the analyses and graphical displays were made using the IBM SPSS STATISTICS 19.0 (IBM Corp., 2010) and ORIGIN (OriginLab, Northampton, MA, USA) software packages respectively.

RESULTS AND DISCUSSION

Runoff Response

During the 30-min rainfall simulation, runoff coefficient for all of the experiments increased rapidly within the first 3-5 min and leveled out as the result of surface saturation and sealing (Figure 2 shows a typical runoff sequence). Indices to describe runoff response for each experiment were calculated and pooled in Table II. It can be seen that time to runoff on all plots was less than 1 min, with the shortest on the 26.8% slope (ranging from 15 to 33 s with the mean value of 23 s). Both flow rate and runoff coefficient showed slightly

Table I.	Models applied to predict interrill soil loss	
Model	1	2

Model	1	2	3	4
Equation	$D_i = K_i IQS_f$	$D_i = K_i IQS$	$D_i = K_i I Q S^{2/3}$	$D_i = K_i I Q^{1/2} S^{2/3}$
Source	Flanagan & Nearing (1995)	Kinnell (1993)	Bulygin <i>et al.</i> (2002)	Zhang <i>et al.</i> (1998)

Where D_i is the delivery of sediment from interrill areas (kg s⁻¹ m⁻²), K_i is interrill erodibility (kg s m⁻⁴), I is the effective rainfall intensity (m s⁻¹), Q is the runoff rate averaged over the entire runoff interval (m s⁻¹), S is slope gradient (m m⁻¹), and S_f is a slope adjustment factor given by: $S_f = 1.05 - 0.85e^{-4sin\theta}$, where θ is the slope gradient of the surface toward a nearby rill, which equals to the slope gradient of the plot in this study.



Figure 2. Road surface runoff coefficient from a typical rainfall simulation. This figure is available in colour online at wileyonlinelibrary.com/journal/ldr.

ascending trend with slope gradient. In general, runoff coefficient was high on all plots with the mean value higher than 0.8.

In order to better explore the factors influencing road surface runoff response, a Pearson correlation was carried out (Table III); this showed that runoff rate, time to runoff, and runoff coefficient were significantly correlated to rainfall intensity and initial soil moisture. However, surface runoff response was statistically independent of slope gradient and bulk density.

Soil Loss Response

Soil loss is shown in Figure 3. Almost all curves showed the highest soil loss rates at the first sample. Soil loss rate decreased with time as the loose materials were washed away. With the same slope gradient, soil loss would usually be intensified as the rainfall intensity increased. This implies that high-intensity rainstorms have a strong ability to splash and transport soil particles; additionally, sealed road surface would accelerate runoff flow and therefore enhance soil loss.

On the other hand, soil loss curve under high rainfall intensities would decrease more quickly than that under the low rainfall intensities. As the slope gradients increased, the gaps between soil loss rates of different rainfall intensities would be enlarged. On the 26.8% slope, soil loss rate under the 142.2 mm h^{-1} rainfall was one order of magnitude higher than that under the 43.8 mm h^{-1} rainfall. Table II showed that the average soil loss rates were increased with slope gradients. Plots on the 26.8% slope had the highest soil loss rate (mean value $0.436 \text{ g s}^{-1} \text{ m}^{-2}$, ranging from 0.097 to $0.877 \text{ g s}^{-1} \text{ m}^{-2}$) among all plots tested.

A Pearson correlation showed that soil loss rate was most significantly related to both runoff rate and rainfall intensity (Table IV). Soil moisture and runoff coefficient were also found to be significantly correlated with soil loss rate. The high soil moisture and runoff coefficient indicated that more overland flow had been generated and more soil detached particles were transported to the outlet of the plot. Nevertheless, both slope gradient and soil bulk density were only weakly correlated with soil loss rate.

Figure 4 shows the relationship between soil loss rate and runoff rate. It has been demonstrated that soil loss rate was linearly increased with runoff rate for the 10.5% slope. When the slope gradient increased, the relationship between soil loss rate and runoff rate changed into power trend, and the exponent value also increased. The rising function exponent showed the increasing erosion intensity on steep slopes. It reflected the aforementioned road surface erosion intensification on steep slopes.

Soil Loss Prediction and Model Development

Stream power has been included in models for sediment entrainment and transport under conditions of shallow flow and rill erosion. The following equation was used to estimate soil loss in our study:

$$q_s = 0.00008\omega - 0.00079$$
 N = 15 R² = 0.907 (3)

where q_s is the unit sediment load (g s⁻¹ cm⁻¹), and ω is stream power (g s⁻³).

Variables		10.5% Slope	17.6% Slope	26.8% Slope	
Initial soil moisture $(g g^{-1})$	Mean	0.155	0.160	0.174	
	Standard deviation	0.012	0.023	0.024	
Bulk density $(g m^{-3})$	Mean	1.594	1.569	1.515	
	Standard deviation	0.047	0.031	0.032	
Time to runoff (s)	Mean	24.2	29.4	23.0	
	Standard deviation	11.30	11.93	6.89	
Runoff rate ($L s^{-1}$)	Mean	0.0242	0.0250	0.0255	
	Standard deviation	0.012	0.012	0.012	
Runoff coefficient (%)	Mean	84.5	86.5	88.5	
	Standard deviation	6.28	4.22	4.46	
Soil loss rate $(g s^{-1} m^{-2})$	Mean	0.228	0.281	0.436	
	Standard deviation	0.126	0.162	0.321	

Table II. Road surface characteristics and indices of runoff and soil loss with different slope gradients^a

^aTotal runoff volume and soil loss for each experiment were obtained by integrating sampled runoff and sediment concentration over time. In turn, runoff rate was calculated as total runoff volume divided by experiment time, runoff coefficient was calculated as total runoff volume divided by total rainfall volume, and soil loss rate was calculated as total soil loss divided by experiment time and plot area.

		Rainfall intensity	Initial soil moisture	Slope	Bulk density
Runoff rate	Pearson r	0.995	0.532	0.067	-0.245
	P (two-tailed)	<0.001*	0.041*	0.813	0.38
	N	15	15	15	15
Time to runoff	Pearson r	-0.875	-0.545	-0.087	0.246
	P (two-tailed)	<0.001*	0.036*	0.758	0.377
	N	15	15	15	15
Runoff coefficient	Pearson r	0.543	0.61	0.268	-0.201
	P (two-tailed)	0.036*	0.016*	0.334	0.472
	N	15	15	15	15

Table III. Pearson correlation between time to runoff, runoff coefficient, and the effective factors

*Marked *p*-values are significant (< 0.05).

Corresponding to the interrill erosion model adopted in WEPP (model 1 in Table I), linear regression analysis with zero intercept was developed between soil loss rate and rainfall characteristics and topography (IQS_f):

$$D_i = 1335793 IQS_f \quad \mathbf{R}^2 = 0.814 \tag{4}$$

where D_i is the delivery of sediment from interrill areas (kg s⁻¹ m⁻²), *I* is the effective rainfall intensity (m s⁻¹), *Q* is the average runoff rate over the entire runoff interval (m s⁻¹), and S_f is a slope adjustment factor. The interrill erodibility on the loess road surface was 1.34×10^6 (kg s m⁻⁴) based on the coefficient of regression equation.

Linear regressions with zero intercept were also carried out for other three selected models (models 2, 3, and 4 in Table I). Regression equations and ME were listed in Table V. Models 1, 2, and 3 in Table V are essentially the same except for different slope factors. The better performance of model 2 over the other two models indicated that the linear slope factor was better than either convex curvilinear or power slope factors in describing the effect of slope steepness for this data set. Similarly, the fact that model 4 was better than model 3 implied that the square root runoff factor was superior to the linear runoff factor. On the basis of the outstanding factors in the selected models, a new equation for road surface interrill erosion prediction was therefore developed (Equation 5).

$$D_i = 12536 \cdot 15 I Q^{1/2} S \quad ME = 0.945 \tag{5}$$

where D_i is the delivery of sediment from interrill areas $(\text{kg s}^{-1} \text{ m}^{-2})$, *I* is the effective rainfall intensity (m s^{-1}) , *Q* is unit discharge (m s^{-1}) , and *S* is slope gradient (m m^{-1}) . The one-to-one line plotted in Figure 5 shows impressive agreement between estimations and observations. The ME value of Equation 5 is higher than all selected models in Table V. It means that the new equation could provide estimations that are very close to measured soil loss rates. Therefore, in this study, Equation 5 is superior to selected models in predicting interrill erosion of unpaved loss road surface.

Implications of the High Erosion Rates on Roads

Unpaved roads can highly modify the hydrological behavior of hillslopes (Jordán et al., 2009). In this study, the short time to runoff and high runoff coefficient showed an acceleration of runoff generation due to road surface compaction. The longer time to runoff on 17.6% slope might be attributed to the plot surface morphology that delayed the flow generation. That is, surface roughness would provide water surface storage in the depressions and alter the flow direction on the surface (Darboux et al., 2001). The slightly ascending trend of flow rate and runoff coefficient reflects the fact that surface runoff would increase with the increase of slope steepness (Morgan, 2005). Generally, when conditions are homogeneous, slope gradient and bulk density would be expected to be positively correlated with the runoff coefficient (Commandeur, 1992). However, runoff response was statistically independent of slope gradient and bulk density on road surface of this study. This unusual finding



Figure 3. Road surface soil loss rates from rainfall simulations on different plots. This figure is available in colour online at wileyonlinelibrary.com/journal/ldr.

Table IV. Pearson correlation between soil loss rate and the effective factors

		Slope	Rainfall intensity	Runoff rate	Initial soil moisture	Bulk density	Runoff coefficient
Soil loss rate	Pearson <i>r</i> <i>P</i> (two-tailed) N	0·421 0·118 15	0·824 <0·001* 15	0·842 <0·001* 15	0.711 0.003* 15	$-0.456 \\ 0.087 \\ 15$	0·565 0·028* 15

*Marked *p*-values are significant (<0.05).

might be explained by the relationship between slope steepness and surface soil bulk density of the plot. A significant negative correlation was found between soil bulk density and slope gradient (Pearson r = -0.71, p = 0.003). It is probably due to the fact that those very steep 26.8% slope roads have less traffic than the less steep ones and, therefore, have less traffic-induced compaction. The effect of higher slope gradient on runoff response is likely to be reduced by lower soil bulk density.

Road surface soil loss was mainly determined by rainfall intensity and runoff rate, reflecting the effect of raindrop impact and flowing water acting together (Kinnell, 2005). The decline speeds of curves in Figure 3 illustrate the soil loss variability, which is controlled by the availability of road surface sediment (Ziegler et al., 2000a). Meanwhile, the unexpected effects of slope gradient and soil bulk density on runoff generation would in turn influence soil loss from road surface. The weak correlation between soil loss rate and slope might show that on some less-compacted steep road surfaces, runoff transport capacity was lower than that on highly compacted gentle slopes. Nevertheless, the low correlation does not imply that slope gradient contribute little to road surface soil loss. In fact, the extremely high soil loss rate on 26.8% slope established that with the increase of rainfall intensity and slope gradient, the raindrop-induced shear forces and the runoff flow velocity would increase, which in turn would intensify erosion (Assouline & Ben-Hur, 2006). Meanwhile, the rising function exponent of regression lines in Figure 4 also reflected the slope effect on road surface soil loss. The linear



Figure 4. Road surface soil loss rates as functions of runoff rates. This figure is available in colour online at wileyonlinelibrary.com/journal/ldr.

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relationship in Figure 4 was similar with previous study that was reported by Huang (1995), and the power trend was comparable to that reported by Meyer & Harmon (1989). Analogous results have been reported by Cao *et al.* (2011) based on field rill overland flow simulation experiments. On their 26.8% slope plots, intensive soil losses were caused by head cutting, thereby leading to a power relationship with a relatively high exponent between soil detachment rate and slope gradient. These results established that slope gradient plays an important role in soil loss on unpaved road surface (Macdonald *et al.*, 2001).

Similar with that reported by Huang (1995), stream power that accounts for the effect of both slope steepness and runoff rate can be used for road surface soil loss prediction. The high determination coefficient of Equation 3 implied that the linear function could provide a reasonable estimation of road surface soil loss. The negative intercept suggested the existence of a threshold stream power for the initiation of the sediment transport process, a common concept in models based on the stream power theory. That is, soil erosion is considered to be a threshold phenomenon, and no soil was entrained when runoff energy was below the threshold stream power (Hairsine & Rose, 1992).

Road surface interrill erodibility calculated in this study was within the range $(1.0-1.8 \times 10^{6} \text{ kg s m}^{-4})$ that was reported by Foltz et al. (2009) on reopened forest road surfaces in northern Idaho, and it was very close to their dry run results $(1.35 \times 10^6 \text{ kg s m}^{-4})$. On the other hand, our result was lower than interrill erodibility of cultivated loess soil $(3.14 \times 10^6 \text{ kg s m}^{-4})$ that was reported by Yang et al. (2003). The result is consistent with that reported by Cao et al. (2011) for rill erosion conditions, implying that at given flow rate and slope gradient conditions, the compacted road surfaces are harder to erode than other land-use categories. However, it cannot be concluded that soil erosion risk on road surfaces is low. The sealed road surfaces could be a considerable source of runoff and have the potential to cause severe soil loss to nearby downstream regions. Furthermore, as reported both by this study and by Cao et al. (2011), road surfaces showed unique hydrological

Table V. Efficiency of models selected

	Equation	ME
Model 1	$D_i = 1335793 \times IQS_f$	0.814
Model 2	$D_i = 2215943 \times IQS$	0.914
Model 3	$D_i = 1321947 \times IQS^{2/3}$	0.893
Model 4	$D_i = 7475 \cdot 28 \times IQ^{1/2}S^{2/3}$	0.927



Figure 5. Comparison of measured and predicted soil loss rates. This figure is available in colour online at wileyonlinelibrary.com/journal/ldr.

characteristics and relatively intensive erosion on steep slope gradient. Hence, the soil loss from the steep road surfaces in watersheds of the Loess Plateau should be treated as a potentially very large contributor to total sediment lost source and should be evaluated precisely. Especially in the wet season, high-intensity storm would further aggravate road-related soil erosion risk. Future research should be conducted in a suitable temporal context of rainfall erosivity to obtain an accurate evaluation of road surface soil loss (Taguas *et al.*, 2011).

CONCLUSIONS

Field rainfall simulation experiments on loess road surfaces were conducted under three slope gradients and five rainfall intensities. The results showed that loess road surfaces quickly generated runoff and produced a high runoff coefficient. During a rainstorm, road surface soil loss rate showed the first flush followed by a reduction with time as the loose materials were washed away. Rainfall intensity, initial soil moisture, and plots slope gradient played important roles in road surface runoff and erosion. Road surfaces showed unique hydrological characteristics and relatively intensive erosion on steep slopes.

Stream power can provide a precise estimation to loess road surface soil loss ($q_s = 0.00008\omega - 0.00079$, $R^2 = 0.907$). Interrill erodibility following the WEPP model was calculated as being 1.34×10^6 (kg s m⁻⁴). On the basis of the comparison of four generally used interrill soil loss models, a new equation composed of rainfall intensity, surface flow discharge, and slope gradient was developed as $D_i = 12536 \cdot 15IQ^{1/2}S$. The results are helpful to develop erosion models and improve the accuracy of existing models based on physical properties for interrill soil loss prediction on loess road surfaces. Also, our results reveal that in order to minimize road-related sediment, a possible action is the designing of proper road drainage and reducing road slope.

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